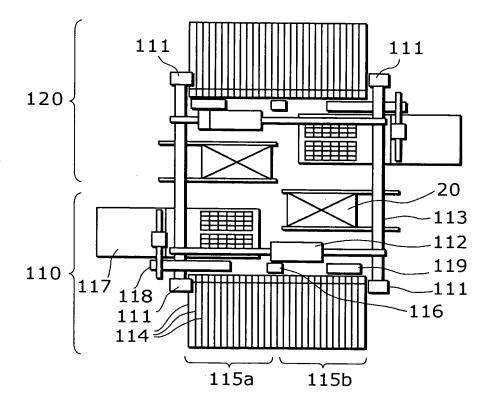


FIG. 2



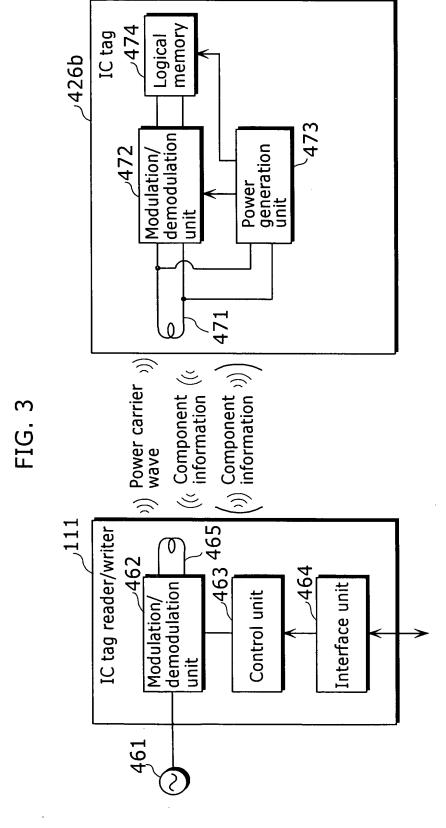
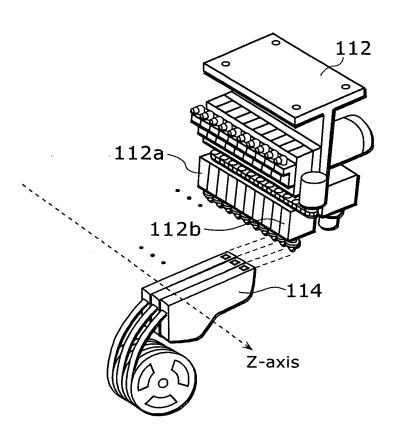
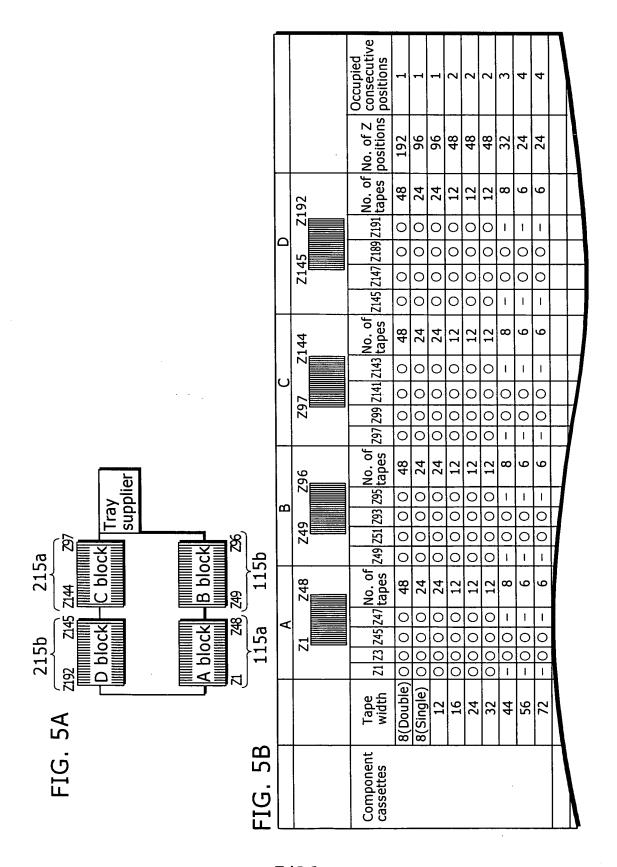


FIG. 4





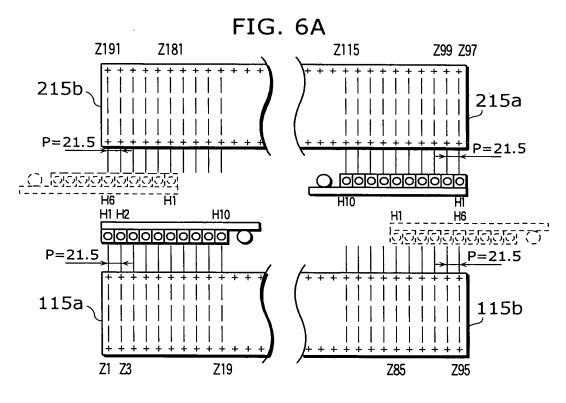


FIG. 6B

10 nozzle heads	Inner side	Z1 Z2	Z3 Z4	Z5 Z6	Z7 Z8	Z9 Z10	Z11 Z12	Z13 Z14	Z15 Z16	Z17 Z18	Z19 ~ Z86	Z87 Z88	Z89 Z90	Z91 Z92	Z93 Z94	Z95 Z96
	Outer side	Z97 Z98	Z99 Z100	Z101 Z102	Z103 Z104	Z105 Z106	Z107 Z108	Z109 Z110	Z111 Z112	Z113 Z114	Z115 ~ Z182	Z183 Z184				Z191 Z192
	H1	0	0	0	0	0	0	0	0	0	0	-	_	_	_	_
	H2	1	0	0	0	0	0	0	0	0	0	0	_	_	_	_
	НЗ	_		0	0	0	0	0	0	0	0	0	0		_	_
	H4	_	-	_	0	0	0	0	0	0	0	0	0	0	_	_
Heads	H5			_	_	0	0	0	0	0	0	0	0	0	0	
(Nozzles)	H6			_	_	1	0	0	0	0	0	0	0	0	0	0
	H7	-	_	_	_	_	-	0	0	0	0	0	0	0	0	0
	H8	<b>-</b> .	_	_		_	-	_	0	0	0	0	0	0	0	0
	H9	_			_	_	_	_		0	0	0	0	0	0	0
	H10	_		_			_		_		0	0	0	0	0	0

○: Picking up possible

-: Picking up impossible

FIG. 7A FIG. 7B FIG. 7C FIG. 7D

423a 423b 423c 423c

FIG. 8

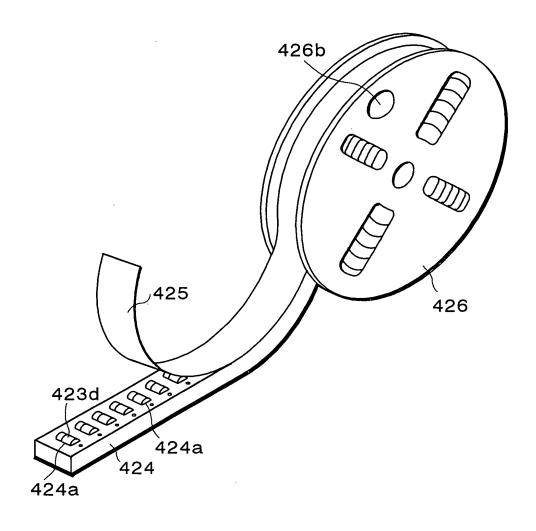
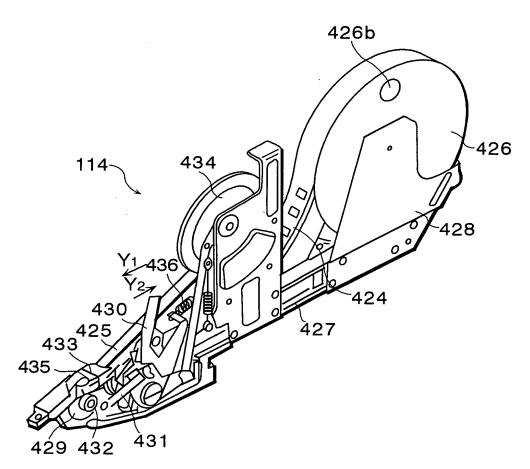
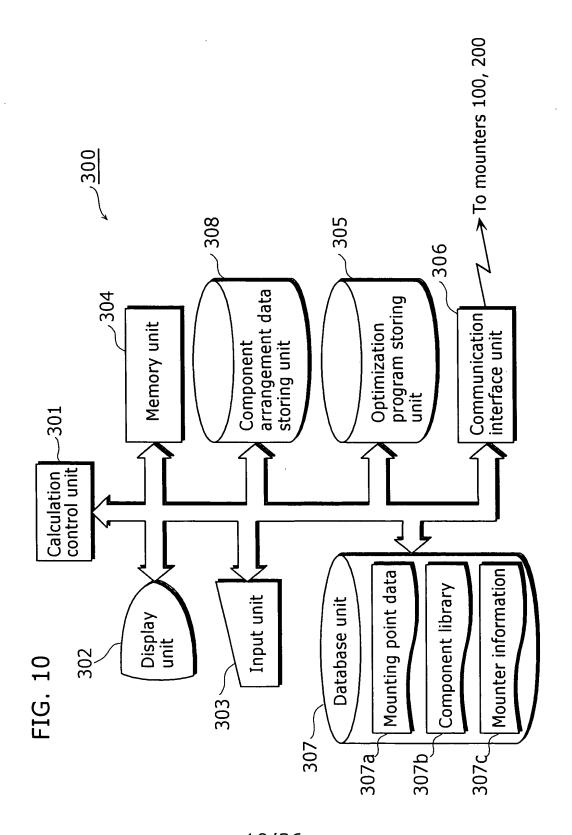


FIG. 9





, a) a)

FIG. 11

,307a

Mounting points pi=(Component type Ci, X coordinate Xi, Y coordinate Yi, Control data  $\phi$ i)

NC data is a list of mounting points pi

NC data =  $\begin{pmatrix} p_1 \\ p_2 \\ p_3 \\ p_3 \\ c_2, x_2, y_2, \phi_2 \\ c_3, x_3, y_3, \phi_3 \\ \vdots \\ p_N \end{pmatrix}$   $\begin{pmatrix} c_1, x_1, y_1, \phi_1 \\ c_2, x_2, y_2, \phi_2 \\ c_3, x_3, y_3, \phi_3 \\ \vdots \\ c_N, x_N, y_N, \phi_N \end{pmatrix}$ 

FIG. 12

				FIG.	. 12	307b		
Component name	(Appea- rance)	3120 (111111)			2-D recognition method	Pick-up nozzle	Tact time (sec.)	Speed XY
				L	metriod		(Sec.)	
0603CR		0.6				SX	0.086	
1005CR		1.0	0.5	0.3-0.5		SA		
1608CR	•	1.6	0.8	0.4-0.8			0.094	
2012CR		2.0	1.25	0.4-0.8		S		
3216CR	:	3.2	1.6	0.4-0.8				1
4TR		2.8	2.8	1.1				
6TR	Series .	4.3	4.5	1.5				
1TIP	ODD	2.0	Ф1.0	-		Cylindrical tip		
2TIP		3.6	Φ1.4	-	Reflection		0.11	
1CAP		3.8	1.9	1.6		(		
2CAP		4.7	2.6	2.1		S		
ЗСАР		6.0	3.2	2.5				
4CAP		7.3	4.3	2.8		М		
SCAP		4.3	4.3	6.0		1*1		
LCAP		6.6	6.6	6.0				
LLCAP		10.3	10.3	10.5		ML	1	
1VOL		4.5	3.8	1.6-2.4		·······	1	
2VOL		3.7	3.0	1.6	]	М	0.13	2
3VOL		4.8	4.0	3.0				

FIG. 13

307c

Unit ID	Head information	Nozzle information	Cassette information	Tray information
110	10 nozzle heads	SX,SA,···	96	8 levels
120	10 nozzle heads	None	96	None
210	4 nozzle heads	S,M,···	48	None

FIG. 14

Component name	Unit ID	Z number		
0603CR	110	5		
1005CR	120	8		
1608CR	210	4		
2012CR	120	22		

FIG. 15

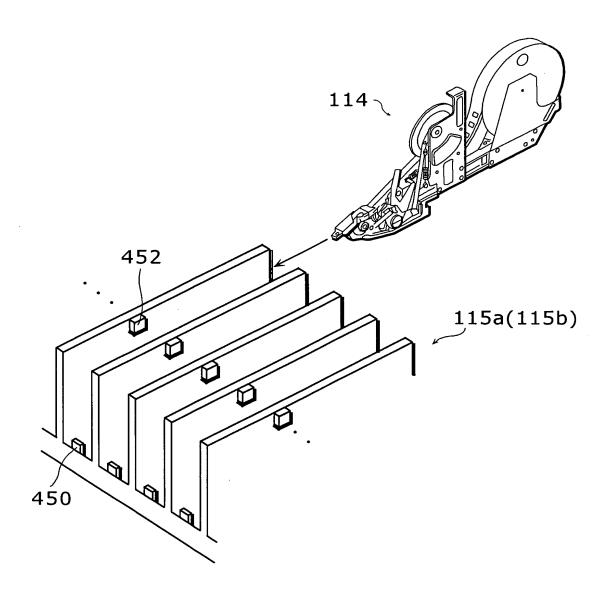


FIG. 16

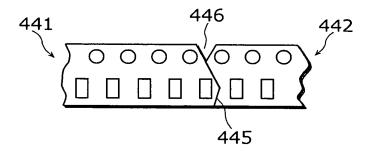
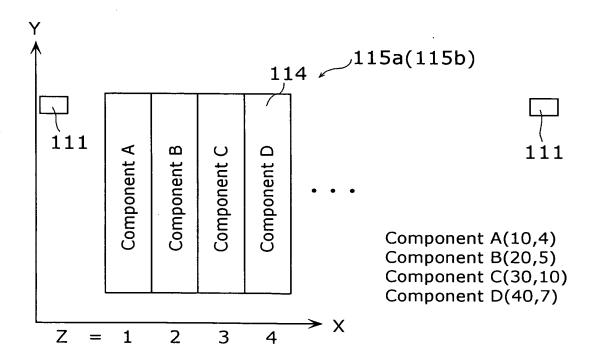


FIG. 17



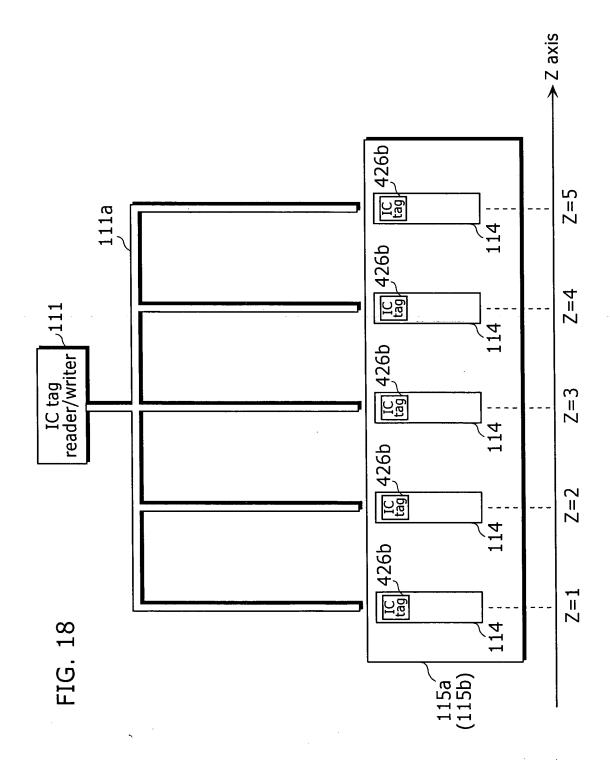


FIG. 19

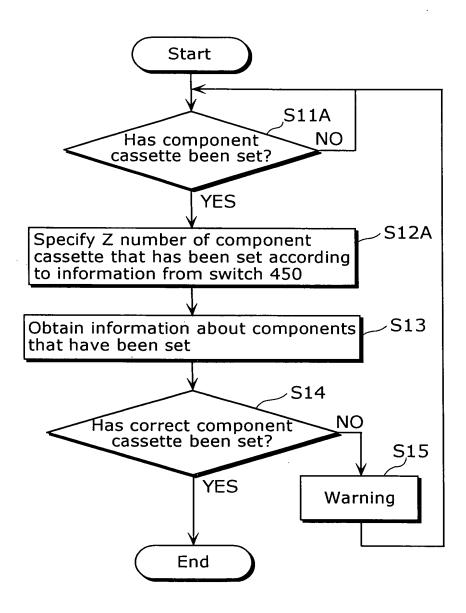


FIG. 20

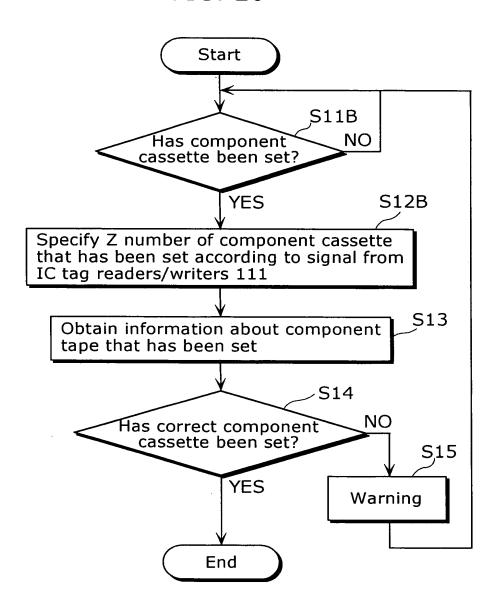


FIG. 21

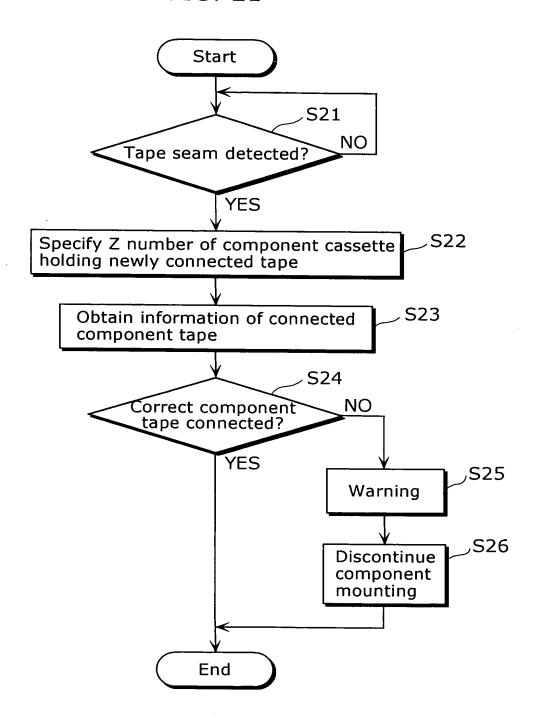
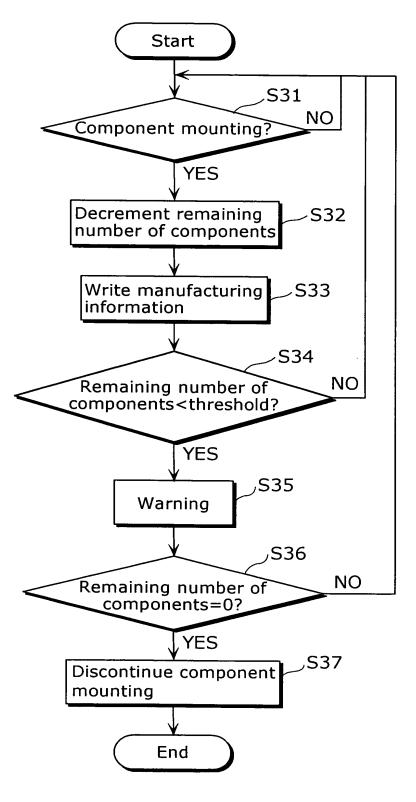


FIG. 22



21/36



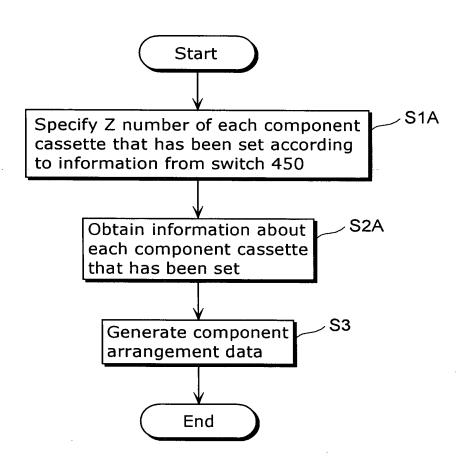


FIG. 24

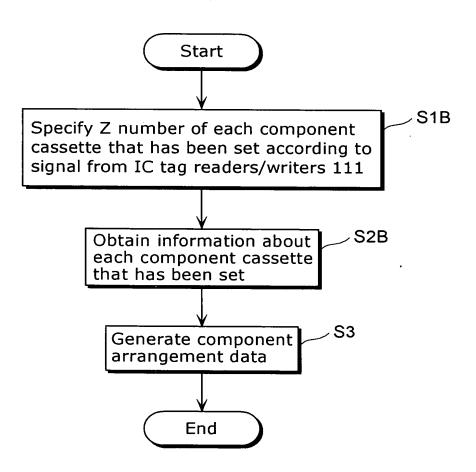
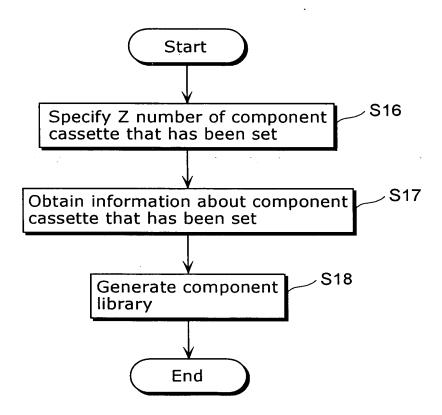
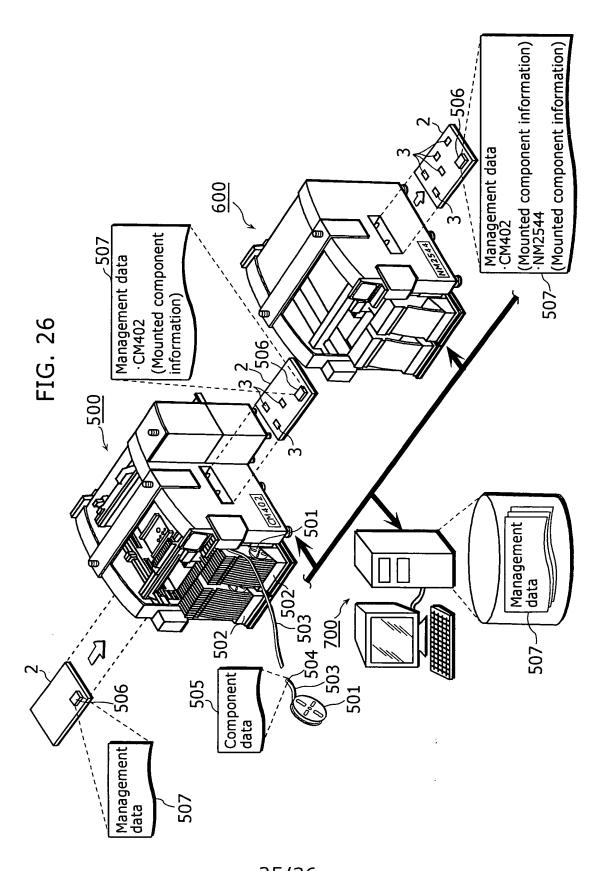
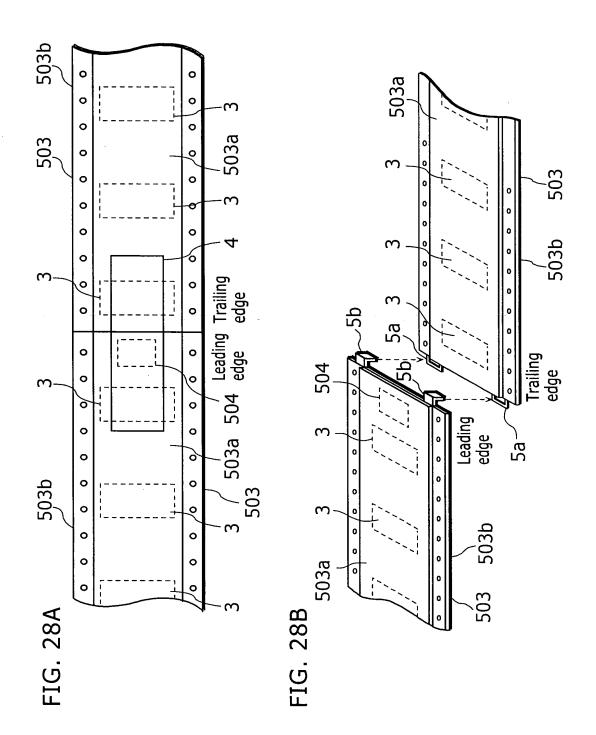
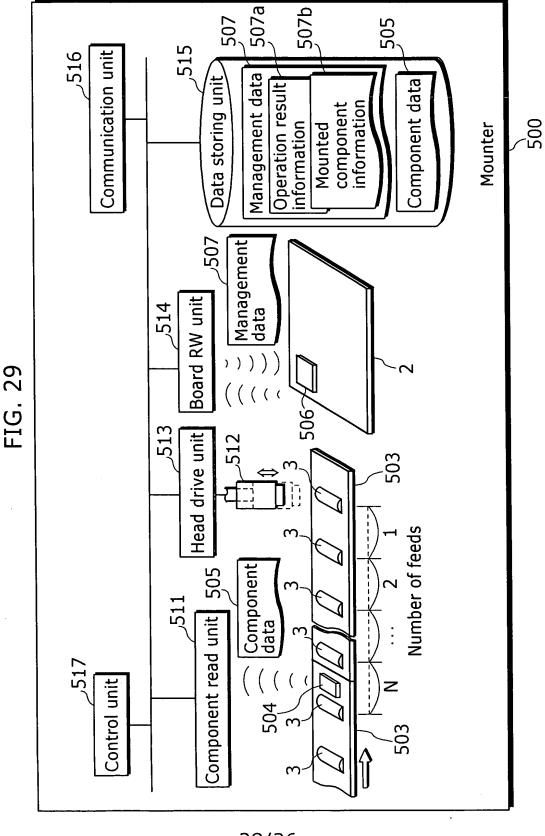


FIG. 25









28/36

FIG. 30

t 7a	_				·	<del></del>	
Operation result information 507a	Bé		Index	Idx 01	:	:	
0.5			Step	100	:	i	
	B5	Error	Code	MC0005	:	:	
			Date/time of occurrence	01/06 35 sec PTESTA 2003/01/06 MC0005 6:34 11:16:55	:	:\	
	B4		PG	PTESTA	i	÷	
Board ID:PB01ID/ Lot number:PB01Rt	Rt B3		iact time	35 sec	:	:	
	B2	Date/time of insertion		2003/01/06 11:16:34	:	:	
Boal	$\frac{1}{100}$		Machine	CM402 2003/0	NM2544		•

FIG. 31

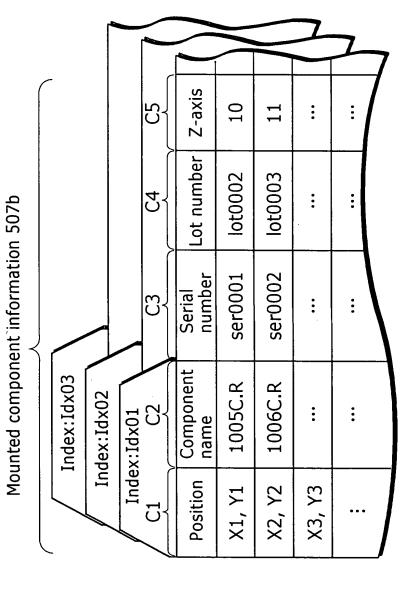
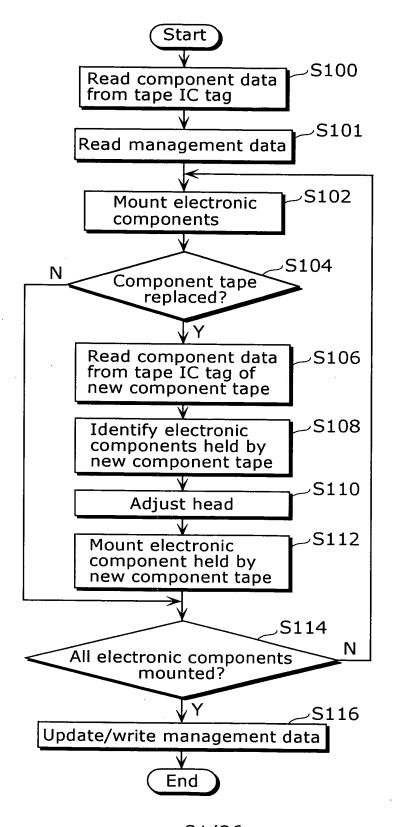
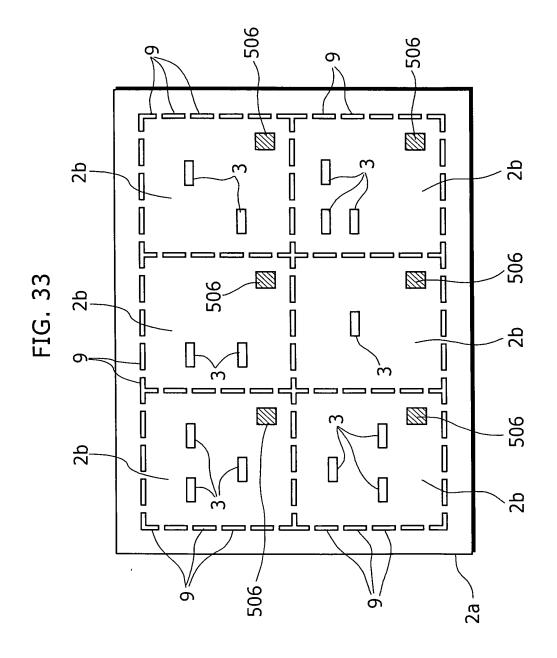


FIG. 32





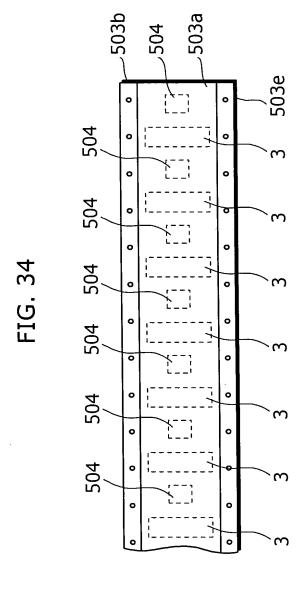


FIG. 35

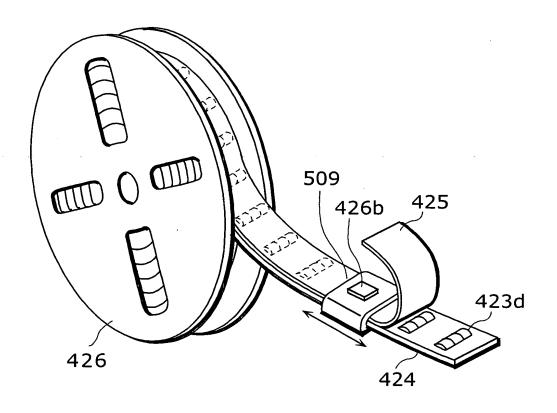


FIG. 36

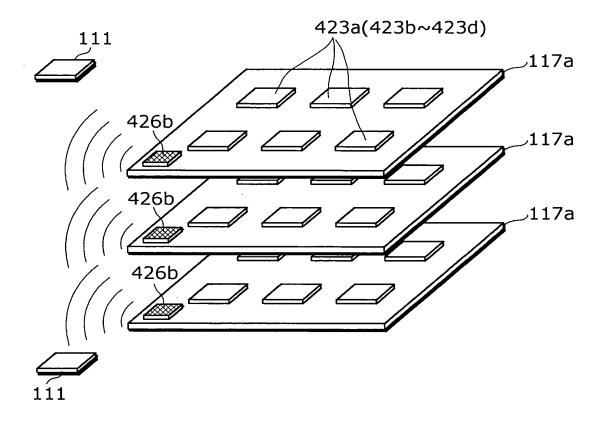


FIG. 37

